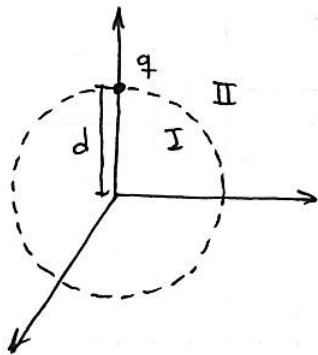


Ejemplo:



$$\varphi(\underline{r}) = \frac{q}{|\underline{r} - d\hat{z}|}$$

Dividimos el espacio en dos zonas

$$\nabla^2 \varphi = 0$$

$$\text{En I: } \varphi_{\text{I}} = \sum_{lm} A_{lm} r^l Y_{lm}$$

$$\text{En II: } \varphi_{\text{II}} = \sum_{lm} \frac{B_{lm}}{r^{l+1}} Y_{lm}$$

y φ debe ser continuo en la interfaz $r=d$

$$\Rightarrow \sum_{lm} A_{lm} d^l Y_{lm}(\theta, \phi) = \sum_{lm} \frac{B_{lm}}{d^{l+1}} Y_{lm}(\theta, \phi) \quad (1)$$

Además

$$-\left. \frac{\partial \varphi_{\text{II}}}{\partial r} \right|_{r=d} + \left. \frac{\partial \varphi_{\text{I}}}{\partial r} \right|_{r=d} = 4\pi \sigma(\theta, \phi)$$

$$\text{con } \sigma = N \delta(\theta) \quad \int \sigma dS = q$$

$$\int \sigma dS = \int N \delta(\theta) d^2 \text{sen} \theta d\theta d\phi = q$$

$$\Rightarrow \sigma(\theta, \phi) = \frac{q \delta(\theta)}{2\pi d^2 \text{sen} \theta}$$

luego

$$\sum_{lm} \left[(l+1) \frac{B_{lm}}{d^{l+2}} + l A_{lm} d^{l-1} \right] Y_{lm}(\theta, \phi) = \frac{4\pi q \delta(\theta)}{2\pi d^2 \text{sen} \theta} \quad (2)$$

De (1)

$$A_{lm} d^l = \frac{B_{lm}}{d^{l+1}} \Rightarrow B_{lm} = A_{lm} d^{2l+1}$$

y de (2), usando ortogonalidad

$$\int Y_{l'm'}^* \sum_{lm} \left[(l+1) \frac{B_{lm}}{d^{l+2}} + l A_{lm} d^{l-1} \right] Y_{lm} d\Omega = \int Y_{l'm'}^* \frac{2q \delta(\theta)}{d^2 \text{sen} \theta} d\Omega$$

$$\Rightarrow \frac{l'+1}{d^{l'+2}} B_{l'm'} + l' d^{l'-1} A_{l'm'} = \frac{4\pi q}{d^2} \sqrt{\frac{2l'+1}{4\pi} \frac{(l'-m')!}{(l'+m')!}} P_l^{m'}(1) \delta_{m',0} \quad (3)$$

luego si $m \neq 0$, $A_{lm} = B_{lm} = 0$ (axisimetría)

$$y \begin{cases} \varphi_I = \sum_l A'_l r^l P_l(\cos \theta) \\ \varphi_{II} = \sum_l \frac{B'_l}{r^{l+1}} P_l(\cos \theta) \end{cases} \begin{matrix} \swarrow \\ \searrow \end{matrix} \begin{matrix} \text{en términos de los} \\ P_l(\cos \theta) \\ \text{en lugar de los } Y_{lm}(\theta, \phi) \\ \text{(requiere cuidado en la} \\ \text{normalización.)} \end{matrix}$$

Usando $B_{lm} = A_{lm} d^{2l+1}$ en (3)

$$\rightarrow A_{l0} d^{l-1} (2l+1) = \frac{4\pi q}{d^2} \sqrt{\frac{2l+1}{4\pi}} P_l(1)$$

coef. de los Y_{lm}

$$\Rightarrow A_{l0} = \frac{q}{d^{2l+1}} \sqrt{\frac{4\pi}{2l+1}} \underbrace{P_l(1)}_1$$

Pero para obtener los A'_l , notar que $\int P_l P_{l'} d\cos \theta d\phi = 2\pi \frac{2}{2l+1} \delta_{ll'}$

$$y \text{ si } f = \sum A'_l P_l(\cos \theta) \Rightarrow A'_l = \frac{2l+1}{4\pi} \int f P_l(\cos \theta) d\cos \theta d\phi$$

$$y A_{l0} = \sqrt{\frac{2l+1}{4\pi}} \int f P_l(\cos \theta) d\cos \theta d\phi$$

$$\Rightarrow A'_\ell = A_{\ell 0} \sqrt{\frac{2\ell+1}{4\pi}}$$

y luego $A'_\ell = \frac{q}{d^{\ell+1}}$ y $B'_\ell = q d^\ell$

$$\Rightarrow \begin{cases} \varphi_I = q \sum_\ell \frac{r^\ell}{d^{\ell+1}} P_\ell(\cos\theta) & r < d \\ \varphi_{II} = q \sum_\ell \frac{d^\ell}{r^{\ell+1}} P_\ell(\cos\theta) & r > d \end{cases}$$

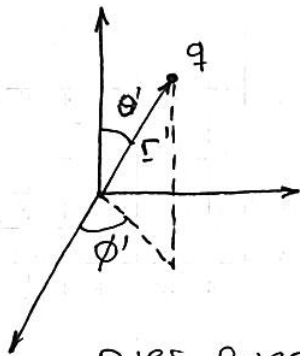
Se introduce notación $r_< = \min\{r, d\}$
 $r_> = \max\{r, d\}$

$$\text{y } \varphi(r) = q \sum_\ell \frac{r_<^\ell}{r_>^{\ell+1}} P_\ell(\cos\theta) = \frac{q}{|r - d\hat{z}|}$$

Desarrollo del pot. debido a una carga puntual en $z=d$

Teorema de adición para armónicos esféricos

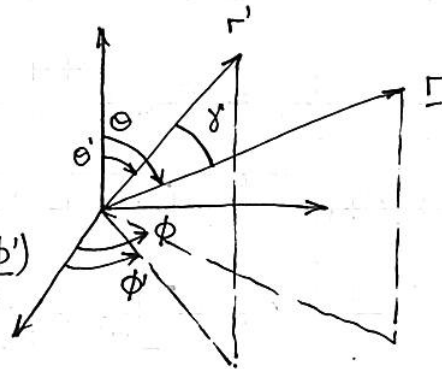
Supongamos que ahora queremos el potencial debido a una carga puntual fuera del eje z .



En general, necesitamos poder expresar los $Y_{\ell m}(\theta, \phi)$ en términos de θ', ϕ' , o equivalentemente, queremos $P_\ell(\cos\gamma)$

pues queremos resolver el problema con

$$\varphi(\theta, \phi) = \frac{q \delta(\theta - \theta') \delta(\phi - \phi')}{r'^2 \sin\theta}$$



Consideremos θ' y ϕ' fijos y desarrollemos

$$P_l(c\delta') = \sum_{l'} \sum_m A_{l'm}(\theta'\phi') Y_{l'm}(\theta\phi)$$

pero cuando $\theta' = 0$ tenemos $P_l(c\theta) = \sum_{l'm} A_{l'm} Y_{l'm}(\theta, \phi)$

y se sigue $l = l'$.

↑
pues

$$c\delta' = \hat{r} \cdot \hat{r}' = s\theta s'\cos(\phi - \phi') + c\theta c\theta'$$

usando $\hat{r} = (s\theta c\phi, s\theta s\phi, c\theta)$
 $\hat{r}' = (s'\theta' c\phi', s'\theta' s\phi', c\theta')$
 y $c(\phi - \phi') = c\phi c\phi' + s\phi s\phi'$

$$\Rightarrow P_l(c\delta') = \sum_m A_{lm}(\theta'\phi') Y_{lm}(\theta\phi)$$

$$\text{con } A_{lm}(\theta'\phi') = \int Y_{lm}^*(\theta\phi) P_l(c\delta') d\Omega$$

que puede interpretarse como los coef. de $\sqrt{\frac{4\pi}{2l+1}} Y_{lm}^*(\theta\phi)$ en una serie de $Y_{l'm'}(\delta\beta) \delta_{m'm}$ con β el ángulo toroidal alrededor de \underline{r}' :

$$A_{lm}(\theta'\phi') = \sqrt{\frac{4\pi}{2l+1}} \int Y_{lm}^*(\theta\phi) \underbrace{\sqrt{\frac{2l'+1}{4\pi}} P_{l'}(c\delta')}_{Y_{l'm'}(\delta\beta) \delta_{m',0}} d\Omega$$

luego

$$\sqrt{\frac{4\pi}{2l+1}} \left[Y_{lm}^*(\theta(\gamma, \beta), \phi(\gamma, \beta)) \right]_{\gamma=0} = \sum_{l'm'} A_{l'm} \sqrt{\frac{2l'+1}{4\pi}} P_{l'}(c\delta')$$

$$\gamma \text{ para } \delta \rightarrow 0 \quad \left. \begin{array}{l} \theta(\gamma, \beta) \rightarrow \theta' \\ \phi(\gamma, \beta) \rightarrow \phi' \end{array} \right\}$$

↑ pero
necesariamente
 $l' = l$
y $m' = 0$

$$\text{y } A_{lm}(\theta', \phi') = \frac{4\pi}{2l+1} Y_{lm}(\theta', \phi')$$

$$\Rightarrow \boxed{P_l(c\delta') = \sum_m \frac{4\pi}{2l+1} Y_{lm}^*(\theta', \phi') Y_{lm}(\theta\phi)}$$

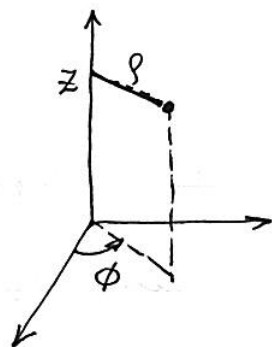
Usando este resultado podemos escribir para la carga q fuera del eje z

$$\varphi(\underline{r}) = \frac{q}{|\underline{r} - \underline{r}'|} = 4\pi q \sum_{\ell, m} \frac{1}{2\ell+1} \frac{r_{<}^{\ell}}{r_{>}^{\ell+1}} Y_{\ell m}^*(\theta', \phi') Y_{\ell m}(\theta, \phi)$$

Coordenadas cilíndricas

En cilíndricas $\nabla^2 \varphi = 0$ con (ρ, ϕ, z)

$$\frac{\partial^2 \varphi}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial \varphi}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 \varphi}{\partial \phi^2} + \frac{\partial^2 \varphi}{\partial z^2} = 0$$



Tomamos $\varphi = R(\rho) Q(\phi) Z(z)$

$$\Rightarrow \underbrace{\frac{1}{R} \left(\frac{d^2}{d\rho^2} + \frac{1}{\rho} \frac{d}{d\rho} \right) R}_{-\lambda} + \frac{1}{\rho^2 Q} \frac{d^2 Q}{d\phi^2} + \underbrace{\frac{1}{Z} \frac{d^2 Z}{dz^2}}_{\lambda} = 0$$

$$\Rightarrow \boxed{\frac{d^2 Z}{dz^2} = \lambda Z} \quad (1)$$

$$\text{Luego } \underbrace{\frac{\rho^2}{R} \left(\frac{d^2}{d\rho^2} + \frac{1}{\rho} \frac{d}{d\rho} \right) R}_{\beta} + \lambda \rho^2 + \underbrace{\frac{1}{Q} \frac{d^2 Q}{d\phi^2}}_{-\beta} = 0$$

$$\Rightarrow \boxed{\frac{d^2 Q}{d\phi^2} = -\beta Q} \quad (2)$$

y finalmente

$$\rho^2 \frac{d^2 R}{d\rho^2} + \rho \frac{dR}{d\rho} = (\beta - \lambda \rho^2) R \quad (3)$$

Veamos la solución en ϕ : De (2)

$$\text{si } \left\{ \begin{array}{l} \beta = -\nu^2 \Rightarrow Q_{\nu} = e^{\nu\phi}, e^{-\nu\phi} \\ \beta = 0 \Rightarrow 1, \phi \\ \beta = \nu^2 \Rightarrow \cos \nu\phi, \text{sen } \nu\phi \end{array} \right.$$

consideremos estos casos (ν entero)

La solución en \mathbb{Z} , de (1)

$$\mathbb{Z}(z) = \begin{cases} e^{kz}, e^{-kz} & \text{si } \lambda = k^2 \\ 1, z & \lambda = 0 \\ \operatorname{sen} kz, \operatorname{cos} kz & \lambda = -k^2 \end{cases}$$